

# Introduction

Travel surveys gather information about travel behavior and often ask participants to manually provide information. To lower user burden, smartphone-based travel surveys use phone sensors to predict trip information. These sensed predictions are not perfectly accurate.

## Goals:

 Provide uncertainty ranges on value estimates that capture the actual value for mode count and distance metrics

## Inputs

- A set of phone-based predictions for counts or distances
- From what we call an *evaluation dataset* • A column-normalized confusion matrix from an existing classifier, so P(true mode | predicted mode) for each entry
- From what we call a *computation dataset*

# Method

For each mode, we use the probabilities to determine the distribution of true counts given predicted counts. Then we add up the true counts from each predicted mode to get the total true count.

For variances, we use a similar method in which we sum up the variances from each predicted mode.



Figure 1. Worked example for mode counts, of the method for computing expected value.

This work was supported in part by the DOE Office of Science, Office of Workforce Development for Teachers and Scientists (WDTS) under the Science Undergraduate Laboratory Internship (SULI) program.

# Estimating mode counts and distances based on phone-sensed predictions

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Distance probabilities for All CEO (left) and Durham (middle) are more similar than MobilityNet (right). This explains why using MobilityNet as the computation dataset failed to produce the expected results.

### Confusion matrix probabilities used for distances



- and over a span of time.



# Conclusion

When probability distributions of the computation and evaluation dataset are too different, uncertainty ranges fail to capture the actual values for all modes. This can be improved in future work, using prior mode distributions to adjust probabilities. When fully implemented, we can reduce mode labeling requirements, and mode usage can be calculated over multiple users



Metric	Computation dataset	<b>Evaluation</b> dataset	Uncertainty range captures actual value?
istance	MobilityNet	AII_CEO	×
istance	MobilityNet	Durham	X
istance	AII_CEO	AII_CEO	
istance	All_CEO	Durham	
istance	Durham	AII_CEO	
Counts	All_CEO	All_CEO	
Counts	All_CEO	Durham	
Counts	Durham	AII_CEO	×

Figure 3. Summary of results over all datasets.

In the last experiment, the uncertainty range for the mode train failed to capture the actual count for train.



Predicted mode

Count probabilities for All CEO (left) and Durham (right) are still different, namely for the mode train. This explains why using Durham as the computation dataset and All CEO as the evaluation dataset failed to produce the expected results.

